



KiCad

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Feedback

Please direct any bug reports, suggestions or new versions to here:

- About KiCad document: <https://gitlab.com/kicad/services/kicad-doc/issues>
- About KiCad software: <https://gitlab.com/kicad/code/kicad/issues>
- About KiCad translation: <https://gitlab.com/kicad/code/kicad-i18n/issues>

Publication date and software version

2015, May 21.

Chapter 1

Introduction

1.1 KiCad

KiCad is an open-source software tool for the creation of electronic schematic diagrams and PCB artwork. Beneath its singular surface, KiCad incorporates an elegant ensemble of the following software tools:

- **KiCad:** Project manager
- **Eeschema:** Schematic editor and component editor
- **Pcbnew:** Circuit board layout editor and footprint editor
- **GerbView:** Gerber viewer

3 utility tools are also included:

- **Bitmap2Component:** Component maker for logos. It creates a schematic component or a footprint from a bitmap picture.
- **PcbCalculator:** A calculator that is helpful to calculate components for regulators, track width versus current, transmission lines, etc.
- **Pl Editor:** Page layout editor.

These tools are usually run from the project manager, but can be also run as stand-alone tools.

KiCad does not present any board-size limitation and it can handle up to 32 copper layers, 14 technical layers and 4 auxiliary layers.

KiCad can create all the files necessary for building printed circuit boards, including:

- Gerber files for photo-plotters
 - drilling files
 - component location files
-

Being open source (GPL licensed), KiCad represents the ideal tool for projects oriented towards the creation of electronic hardware with an open-source flavour.

KiCad is available for Linux, Windows and Apple macOS.

1.2 KiCad files and folders

KiCad creates and uses files with the following specific file extensions (and folders) for schematic and board editing.

Project manager file:

*.pro	Small file containing a few parameters for the current project, including the component library list.
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Schematic editor files:

*.sch	Schematic files, which do not contain the components themselves.
*.lib	Schematic component library files, containing the component descriptions: graphic shape, pins, fields.
*.dcm	Schematic component library documentation, containing some component descriptions: comments, keywords, reference to data sheets.
*__cache.lib	Schematic component library cache file, containing a copy of the components used in the schematic project.
sym-lib-table	Symbol library list (<i>symbol library table</i>): list of symbol libraries available in the schematic editor.

Board editor files and folders:

*.kicad_pcb	Board file containing all info but the page layout.
*.pretty	Footprint library folders. The folder itself is the library.
*.kicad_mod	Footprint files, containing one footprint description each.
*.brd	Board file in the legacy format. Can be read, but not written, by the current board editor.
*.mod	Footprint library in the legacy format. Can be read by the footprint or the board editor, but not written.
fp-lib-table	Footprint library list (<i>footprint library table</i>): list of footprint libraries (various formats) which are loaded by the board or the footprint editor or CvPcb.

Common files:

*.kicad_wks	Page layout description files, for people who want a worksheet with a custom look.
*.net	Netlist file created by the schematic, and read by the board editor. This file is associated to the .cmp file, for users who prefer a separate file for the component/footprint association.

Special file:

*.cmp	Association between components used in the schematic and their footprints. It can be created by Pcbnew and imported by Eeschema. Its purpose is to import changes from Pcbnew to Eeschema, for users who change footprints inside Pcbnew (for instance using <i>Exchange Footprints</i> command) and want to import these changes in schematic.
-------	---

Other files:

They are generated by KiCad for fabrication or documentation.

*.gbr	Gerber files, for fabrication.
*.drl	Drill files (Excellon format), for fabrication.
*.pos	Position files (ASCII format), for automatic insertion machines.
*.rpt	Report files (ASCII format), for documentation.
*.ps	Plot files (Postscript), for documentation.
*.pdf	Plot files (PDF format), for documentation.
*.svg	Plot files (SVG format), for documentation.
*.dxf	Plot files (DXF format), for documentation.
*.plt	Plot files (HPGL format), for documentation.

Chapter 2

Installation and configuration

2.1 Display options

Hardware accelerated renderer in Pcbnew and Gerbview requires video card with support of OpenGL v2.1 or higher.

2.2 Initialization of the default configuration

The default configuration file named **kicad.pro** is supplied in `kicad/template`. It serves as a template for any new project and is used to set the list of library files loaded by Eeschema. A few other parameters for Pcbnew (default text size, default line thickness, etc.) are also stored here.

Another default configuration file named **fp-lib-table** may exist. It will be used only once to create a footprint library list; otherwise the list will be created from scratch.

2.3 Modifying the default configuration

The default **kicad.pro** file can be freely modified, if desired.

Verify that you have write access to `kicad/template/kicad.pro`

Run KiCad and load **kicad.pro** project.

Run Eeschema via KiCad manager. Modify and update the Eeschema configuration, to set the list of libraries you want to use each time you create new projects.

Run Pcbnew via KiCad manager. Modify and update the Pcbnew configuration, especially the footprint library list. Pcbnew will create or update a library list file called **footprint library table**. There are 2 library list files (named `fp-lib-table`): The first (located in the user home directory) is global for all projects and the second (located in the project directory) is optional and specific to the project.

2.4 Paths configuration

In KiCad, one can define paths using an *environment variable*. A few environment variables are internally defined by KiCad, and can be used to define paths for libraries, 3D shapes, etc.

This is useful when absolute paths are not known or are subject to change (e.g. when you transfer a project to a different computer), and also when one base path is shared by many similar items. Consider the following which may be installed in varying locations:

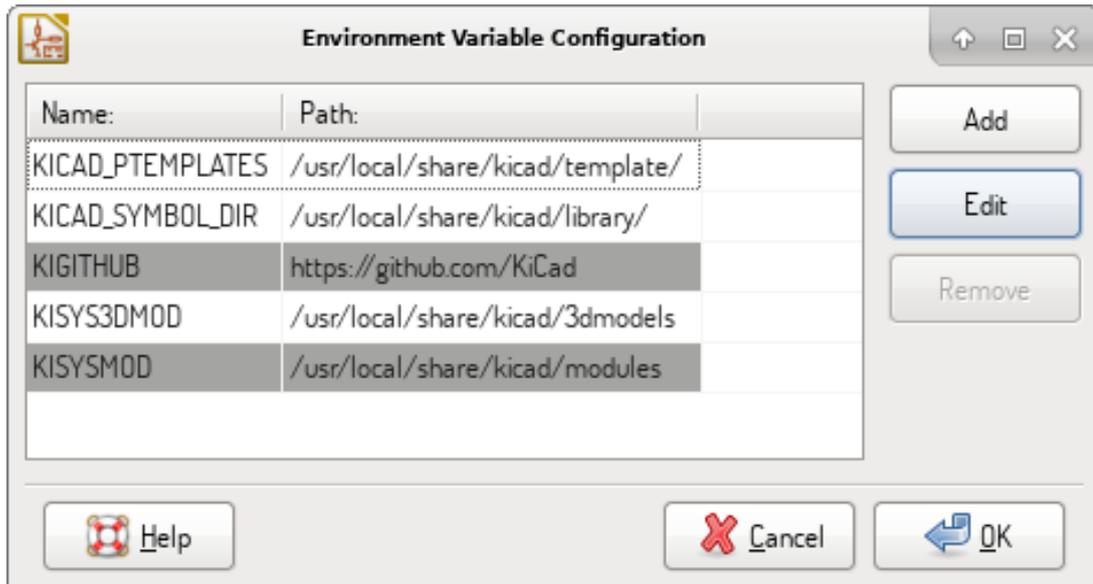
- Eeschema component libraries
- Pcbnew footprint libraries
- 3D shape files used in footprint definitions

For instance, the path to the *connect.pretty* footprint library, when using the **KISYSMOD** environment variable, would be defined as ***\${KISYSMOD}/connect.pretty***

This option allows you to define a path using an environment variable, and add your own environment variables to define personal paths, if needed.

KiCad environment variables:

KICAD_PTEMPLATE	Templates used during project creation (DEPRECATED as of version 5.0.0-rc2, use KICAD_TEMPLATE_DIR instead). If you are using this variable, it must be defined.
KICAD_SYMBOL_DIR	Base path of symbol library files.
KIGITHUB	Frequently used in example footprint lib tables. If you are using this variable, it must be defined.
KISYS3DMOD	Base path of 3D shapes files, and must be defined because an absolute path is not usually used.
KISYSMOD	Base path of footprint library folders, and must be defined if an absolute path is not used in footprint library names.
KICAD_TEMPLATE_DIR	Location of templates installed with KiCad.
KICAD_USER_TEMPLATE_DIR	Location of personal templates.



Note also the environment variable **KIPRJMOD** is **always** internally defined by KiCad, and is the **current project absolute path**.

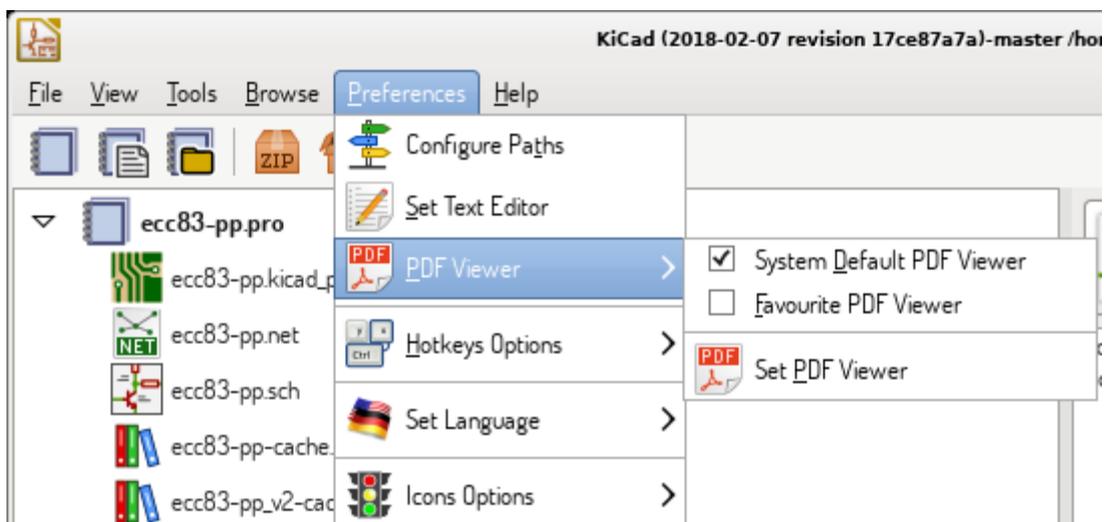
For instance, $\${KIPRJMOD}/connect.pretty$ is always the *connect.pretty* folder (the pretty footprint library) found inside the **current project folder**.

If you modify the configuration of paths, please quit and restart KiCad to avoid any issues in path handling.

2.5 Initialization of external utilities

You may define your favorite text editor and PDF viewer. These settings are used whenever you want to open a text or PDF file.

These settings are accessible from the Preference menu:



2.5.1 Selection of text editor

Before using a text editor to browse/edit files in the current project, you must choose the text editor you want to use. Select *Preferences* → *Set Text Editor* to set the text editor you want to use.

2.5.2 Selection of PDF viewer

You may use the default PDF viewer or choose your own.

To change from the default PDF viewer use *Preferences* → *PDF Viewer* → *Set PDF Viewer* to choose the PDF viewer program, then select *Preferences* → *PDF Viewer* → *Favourite PDF Viewer*.

On Linux the default PDF viewer is known to be fragile, so selecting your own PDF viewer is recommended.

2.6 Creating a new project

In order to manage a KiCad project consisting of schematic files, printed circuit board files, supplementary libraries, manufacturing files for photo-tracing, drilling and automatic component placement files, it is recommended to create a project as follows:

- **Create a working directory for the project** (using KiCad or by other means).
- **In this directory, use KiCad to create a project file** (file with extension .pro) via the "Create a new project" or "Create a new project from template" icon.



Warning

Use a unique directory for each KiCad project. Do not combine multiple projects into a single directory.

KiCad creates a file with a .pro extension that maintains a number of parameters for project management (such as the list of libraries used in the schematic). Default names of both main schematic file and printed circuit board file are derived from the name of the project. Thus, if a project called **example.pro** was created in a directory called **example**, the default files will be created:

example.pro	Project management file.
example.sch	Main schematic file.
example.kicad_pcb	Printed circuit board file.
example.net	Netlist file.
example.*	Various files created by the other utility programs.
example-cache.lib	Library file automatically created and used by the schematic editor containing a backup of the components used in the schematic.

2.7 Importing a foreign project

KiCad is able to import files created using other software packages. Currently only Eagle 6.x or newer (XML format) is supported.

To import a foreign project, you need to select either a schematic or a board file in the import file browser dialog. Imported schematic and board files should have the same base file name (e.g. project.sch and project.brd). Once the requested files are selected, you will be asked to select a directory to store the imported files, which are going to be saved as a KiCad project.

Chapter 3

Using KiCad project manager

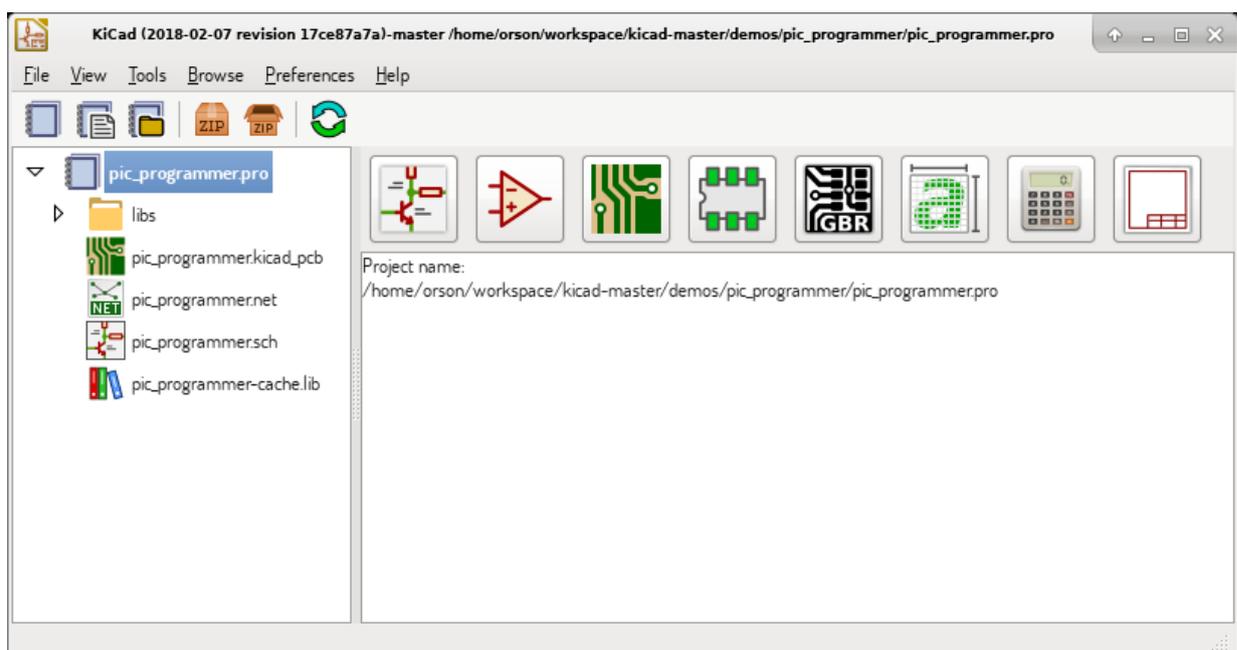
KiCad project manager (kicad or kicad.exe) is a tool which can easily run the other tools (schematic and PCB editors, Gerber viewer and utility tools) when creating a design.

Running the other tools from KiCad manager has some advantages:

- cross probing between schematic editor and board editor.
- cross probing between schematic editor and footprint selector (CvPcb).

However, you can only edit the current project files. When these tools are run in *stand alone* mode, you can open any file in any project but cross probing between tools can give strange results.

3.1 Project manager window



The main KiCad window is composed of a project tree view, a launch pane containing buttons used to run the various software tools, and a message window. The menu and the toolbar can be used to create, read and save project files.

3.2 Utility launch pane

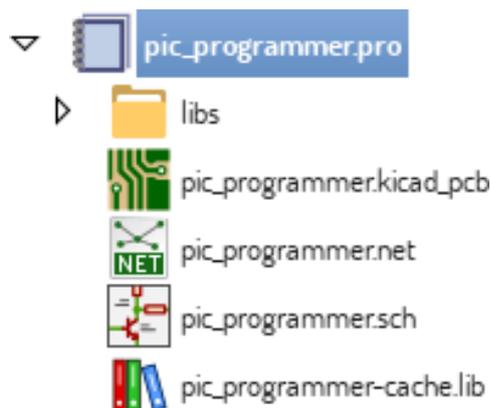
KiCad allows you to run all standalone software tools that come with it.

The launch pane is made of the 8 buttons below that correspond to the following commands (1 to 8, from left to right):



1	Eeschema	Schematic editor.
2	LibEdit	Component editor and component library manager.
3	Pcbnew	Board layout editor.
4	FootprintEditor	Footprint editor and footprint library manager.
5	Gerbview	Gerber file viewer. It can also display drill files.
6	Bitmap2component	Tool to build a footprint or a component from a B&W bitmap image to create logos.
7	Pcb Calculator	Tool to calculate track widths, and many other things.
8	Pl Editor	Page layout editor, to create/customize frame references.

3.3 Project tree view



Double-clicking on the schematic file runs the schematic editor, in this case opening the file **pic_programmer.sch**.

Double-clicking on the board file runs the layout editor, in this case opening the file **pic_programmer.kicad_pcb**.

Right clicking on any of the files in the project tree allows generic file manipulation.

3.4 Top toolbar



KiCad top toolbar allows for some basic file operations:

	Create a new project. If the default template file (kicad.pro) is found in kicad/template , it is copied into the working directory.
	Create a new project from an existing template.
	Open an existing project.
	Update and save the current project tree.
	Create a zip archive of the whole project. This includes schematic files, libraries, PCB, etc.
	Refresh the tree view, sometimes needed after a tree change.

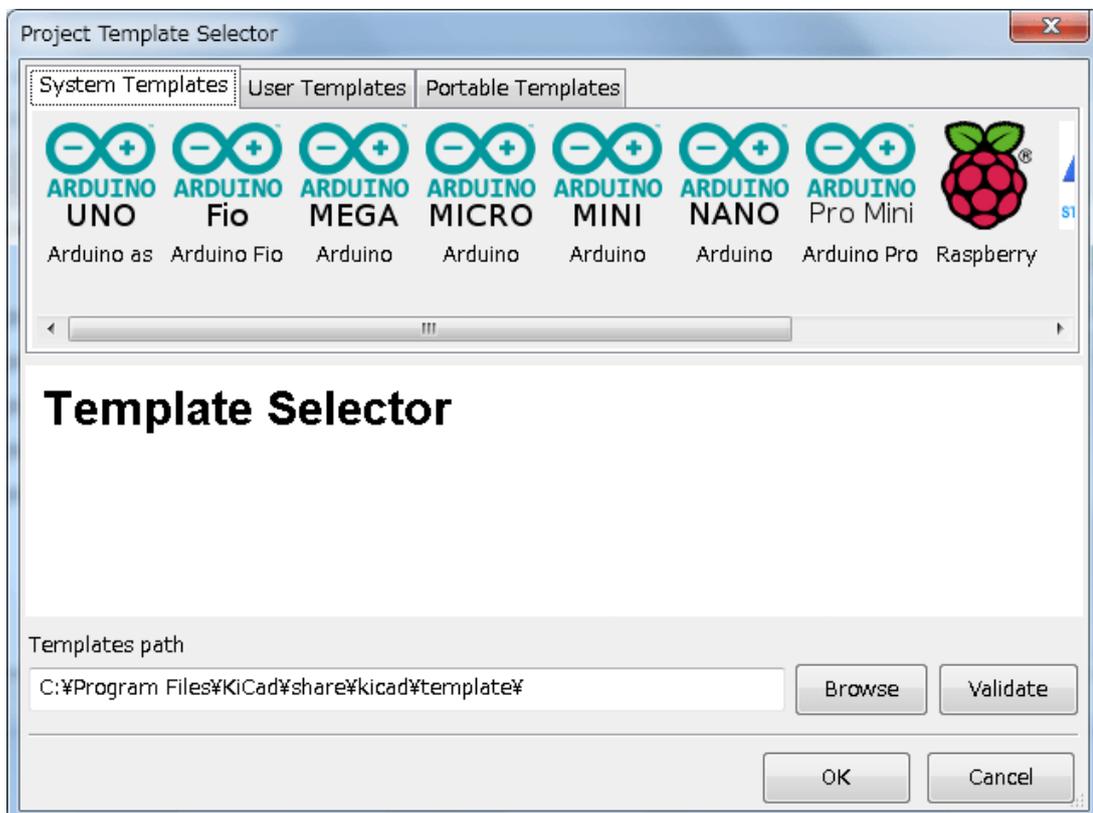
Chapter 4

Project templates

Using a project template facilitates setting up a new project with predefined settings. Templates may contain pre-defined board outlines, connector positions, schematic elements, design rules, etc. Complete schematics and/or PCBs used as seed files for the new project may even be included.

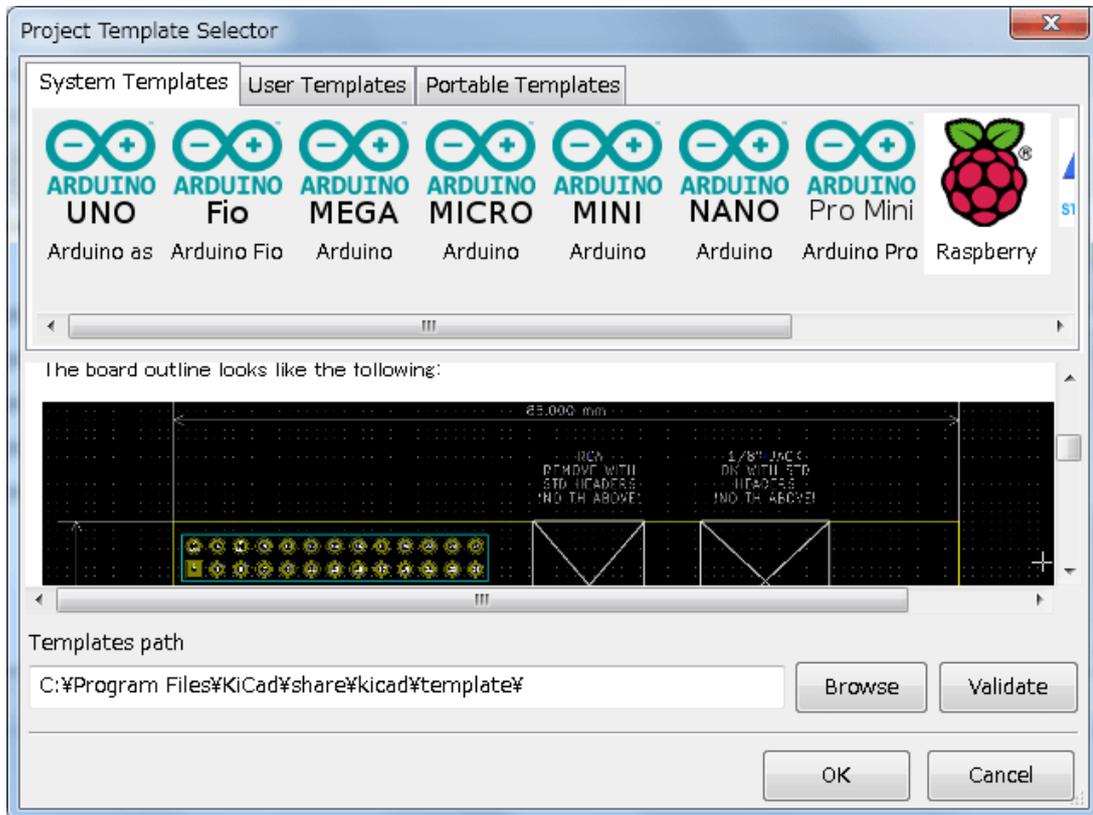
4.1 Using templates

The *File* → *New Project* → *New Project from Template* menu will open the Project Template Selector dialog:



A single click on a template's icon will display the template information, and a further click on the OK button creates the new project. The template files will be copied to the new project location and renamed to reflect the new project's name.

After selection of a template:



4.2 Template Locations:

KiCad looks for template files in the following paths:

- path defined in the environment variable `KICAD_USER_TEMPLATE_DIR`
- path defined in the environment variable `KICAD_TEMPLATE_DIR`
- System templates: `<kicad bin dir>/../share/kicad/template/`
- User templates:
 - Unix: `~/kicad/templates/`
 - Windows: `C:\Documents and Settings\username\My Documents\kicad\templates`
 - Mac: `~/Documents/kicad/templates/`
- When the environment variable `KICAD_PTEMPLATES` is defined there is a third tab, Portable Templates, which lists templates found at the `KICAD_PTEMPLATES` path (DEPRECATED).

4.3 Creating templates

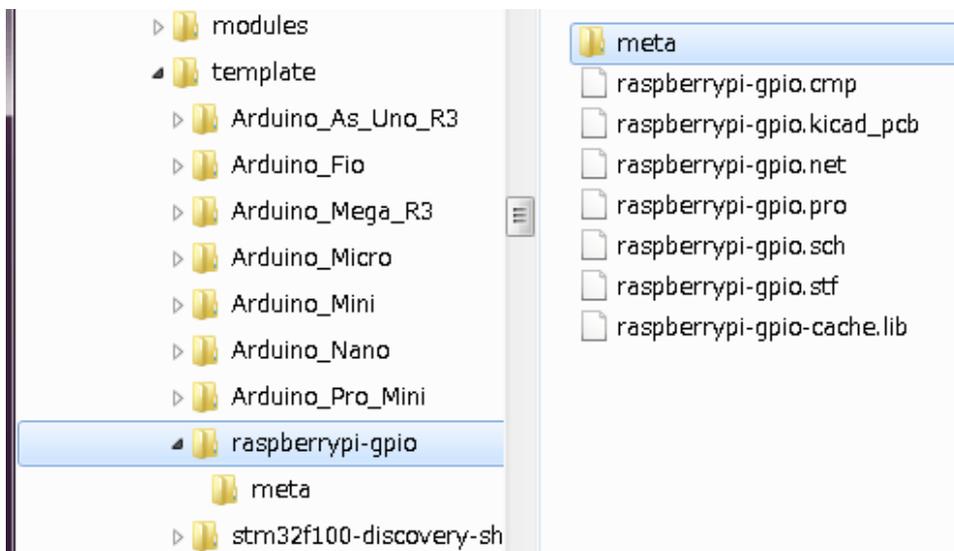
The template name is the directory name where the template files are stored. The metadata directory is a subdirectory named **meta** containing files describing the template.

All files and directories in a template are copied to the new project path when a project is created using a template, except **meta**.

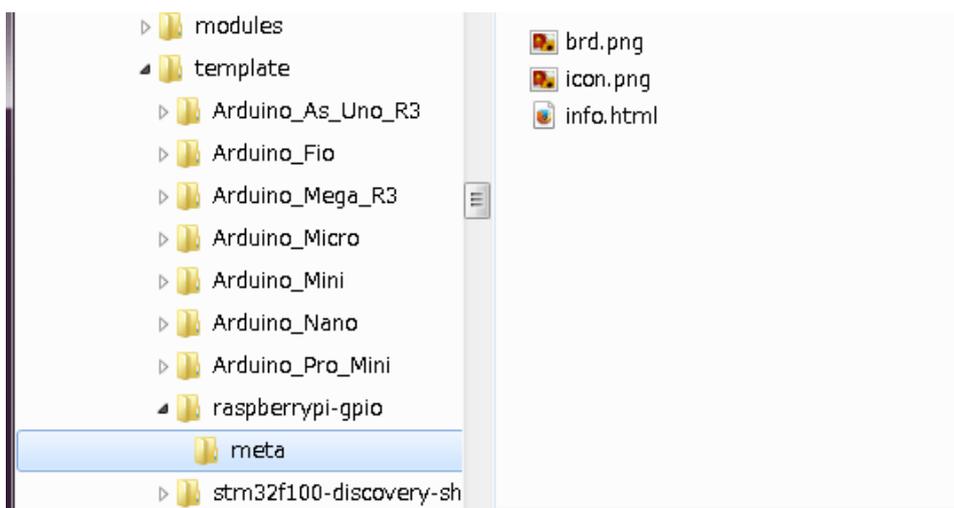
When a new project is created from a template, all files and directories starting with the template name will be renamed with the new project file name, excluding the file extension.

The metadata consists of one required file, and may contain optional files. All files must be created by the user using a text editor or previous KiCad project files, and placed into the required directory structure.

Here is an example showing project files for **raspberrypi-gpio** template:



And the metadata files:



4.3.1 Required File:

meta/info.html	HTML-formatted information describing the template.
----------------	---

The `<title>` tag determines the actual name of the template that is exposed to the user for template selection. Note that the project template name will be cut off if it's too long. Due to font kerning, typically 7 or 8 characters can be displayed.

Using HTML means that images can be easily in-lined without having to invent a new scheme. Only basic HTML tags can be used in this document.

Here is a sample **info.html** file:

```
<!DOCTYPE HTML PUBLIC "-//W3C//DTD HTML 4.0 Transitional//EN">
<HTML>
<HEAD>
<META HTTP-EQUIV="CONTENT-TYPE" CONTENT="text/html;
charset=windows-1252">
<TITLE>Raspberry Pi - Expansion Board</TITLE>
</HEAD>
<BODY LANG="fr-FR" DIR="LTR">
<P>This project template is the basis of an expansion board for the
<A HREF="http://www.raspberrypi.org/" TARGET="blank">Raspberry Pi $25
ARM board.</A> <BR><BR>This base project includes a PCB edge defined
as the same size as the Raspberry-Pi PCB with the connectors placed
correctly to align the two boards. All IO present on the Raspberry-Pi
board is connected to the project through the 0.1" expansion
headers. <BR><BR>The board outline looks like the following:
</P>
<P><IMG SRC="brd.png" NAME="brd" ALIGN=BOTTOM WIDTH=680 HEIGHT=378
BORDER=0><BR><BR><BR><BR>
</P>
<P>(c)2012 Brian Sidebotham<BR>(c)2012 KiCad Developers</P>
</BODY>
</HTML>
```

4.3.2 Optional Files:

meta/icon.png	A 64 x 64 pixel PNG icon file which is used as a clickable icon in the template selection dialog.
---------------	---

Any other image files used by **meta/info.html**, such as the image of the board file in the dialog above, are placed in this folder as well.

Part I

Upgrading from Version 4 to Version 5

Changes were made to the behavior to KiCad during the version 5 development that can impact projects created with older versions of KiCad. This section serves as a guide to ensure the smoothest possible path when upgrading to version 5 of KiCad.

Chapter 5

Schematic Symbol Libraries

Schematic symbol libraries are no longer accessed using a symbol (referred to as components in version 4) look up list. Symbol libraries are now managed by a symbol library table that behaves similarly to the footprint library table. This change is a significant improvement, but some schematics may need manual intervention when being converted to version 5.

In previous versions, KiCad used a list of library files to search when locating symbols in the Eeschema file. When locating a symbol, each path would be searched and the first library that held the symbol name would be used.

From v5, KiCad symbol names are prefixed with a nickname, and a [lookup table matching nicknames to library paths](#) is used to locate the library which holds the symbol. The table is called the *symbol library table* and built from configuration files stored in the user's KiCad configuration directory and the currently loaded project directory.

To upgrade a KiCad project from v4 to v5, nicknames for all of the library files need to be created and then schematic symbol names need to be prefixed with the correct nickname.

5.1 Global Symbol Library Table.

Eeschema v5 will automatically create a global symbol table when first started. You will be given a chance to skip this and create your own global symbol table by hand. You only need to do this if don't use KiCad symbol libraries at all. Otherwise it is easier to modify the automatically generated global symbol table.

Note

If you track the [symbol library repository](#), changes made to the default global symbol library table are not tracked by KiCad. You will have to manually keep the global symbol library table up to date.

5.2 Symbol Library Table Mapping

Automatic remapping of symbols will be executed whenever a schematic is opened that has not been remapped. There are a few steps you should take ahead of time in order for the remapping to be the most effective.

Note

If you have been using a development build of KiCad, copy the full default global symbol library table file (sym-lib-table) from the template folder installed with the KiCad libraries or from the [KiCad library repo](#) to your KiCad user configuration folder. This will replace the empty one (most likely) created by Eeschema. If you do not do this, you will most likely end up with a bunch of broken symbol links.

**Warning**

Remapped schematics will not be compatible with older versions of KiCad. The Remap Symbols dialog will make a backup of your schematic files and you should do the same if you remap manually.

1. If possible, keep version 4 of KiCad installed on your system unless you have never used any of the symbol libraries distributed with KiCad.
 2. If you get warning about missing libraries when you start version 4 of Eeschema, make sure to fix the missing libraries if they contain symbols that are in the schematic before you attempt to remap your schematic. Otherwise, the correct symbol will not be found and you will end up with broken symbol links in your schematic. You can test this by left clicking on a symbol in the schematic and verifying that the symbol is not being loaded from the cache library. If a symbol is being loaded from the cache library, Eeschema cannot find your part in the system or project symbol libraries. If you need a cached part to be available to other projects on your system, you will need to integrate it into a system or project library manually.
 3. If symbol recovery is required during the remapping process, do not dismiss it. Failure to recover symbols will result in broken symbol links or the wrong symbol being linked in the schematic.
 4. During the remapping process, symbol libraries not found in the global symbol library table will be used to create a project specific symbol library table. You can move them manually to the global symbol library table if that is your preference.
 5. For the most accurate remapping, create a project library by copying the project cache file (project-name-cache.lib) to a different file and add it to the top of the symbol library list. You must use a version of KiCad prior to the symbol library table implementation in order to do this.
-

Note

A tool has been provided to attempt to fix remapping issues. If there are missing symbol library links in a schematic, they can be fixed by opening the "Tools→Edit Symbol Library References..." menu entry and clicking on the "Map Orphans" button.

5.3 Remapping Search Order

When remapping symbols, KiCad proceeds in the following order to assign the library to a symbol:

1. Global Symbol Library Table: Symbols are preferentially mapped to the global symbol library table, if one exists.
-

2. Project specific libraries: Libraries listed in the project library list that are not in the global symbol library table are searched next.
3. Project cache file: If a symbol doesn't exist in the listed libraries above, it is first rescued — a copy is made from the cache and placed in the *proj-rescue.lib* — before the symbol is mapped to this new, rescue library.

5.4 Symbol Names and Symbol Library Nickname Limitations

Symbol names may not contain <SPACE>, ':', '/'.

Library nicknames may not contain <SPACE>, ':', '/'.

Existing symbol names with these characters must be renamed by manually editing the relevant schematic and library files.

Chapter 6

Symbol Cache Library Availability

The cache library is no longer shown in either the symbol library viewer or the symbol library editor. The cache should never be edited because any changes are overwritten by the next schematic save.

Chapter 7

Board File Format Changes

Several new features have been added to Pcbnew which impact the board file format. Using these new features in board designs will prevent them from being opened with previous versions of Pcbnew.

- Rounded rectangle footprint pads.
- Custom shape footprint pads.
- Footprint pad names longer than four characters.
- Keep out zones on more than a single layer.
- 3D models offset saved as millimeters instead of inches.
- Footprint text locking.

7.1 Global Footprint Library Table.

If you track the [footprint library repository](#), changes made to the default global footprint library table are not tracked by KiCad. You will have to manually keep the global footprint library table up to date.
